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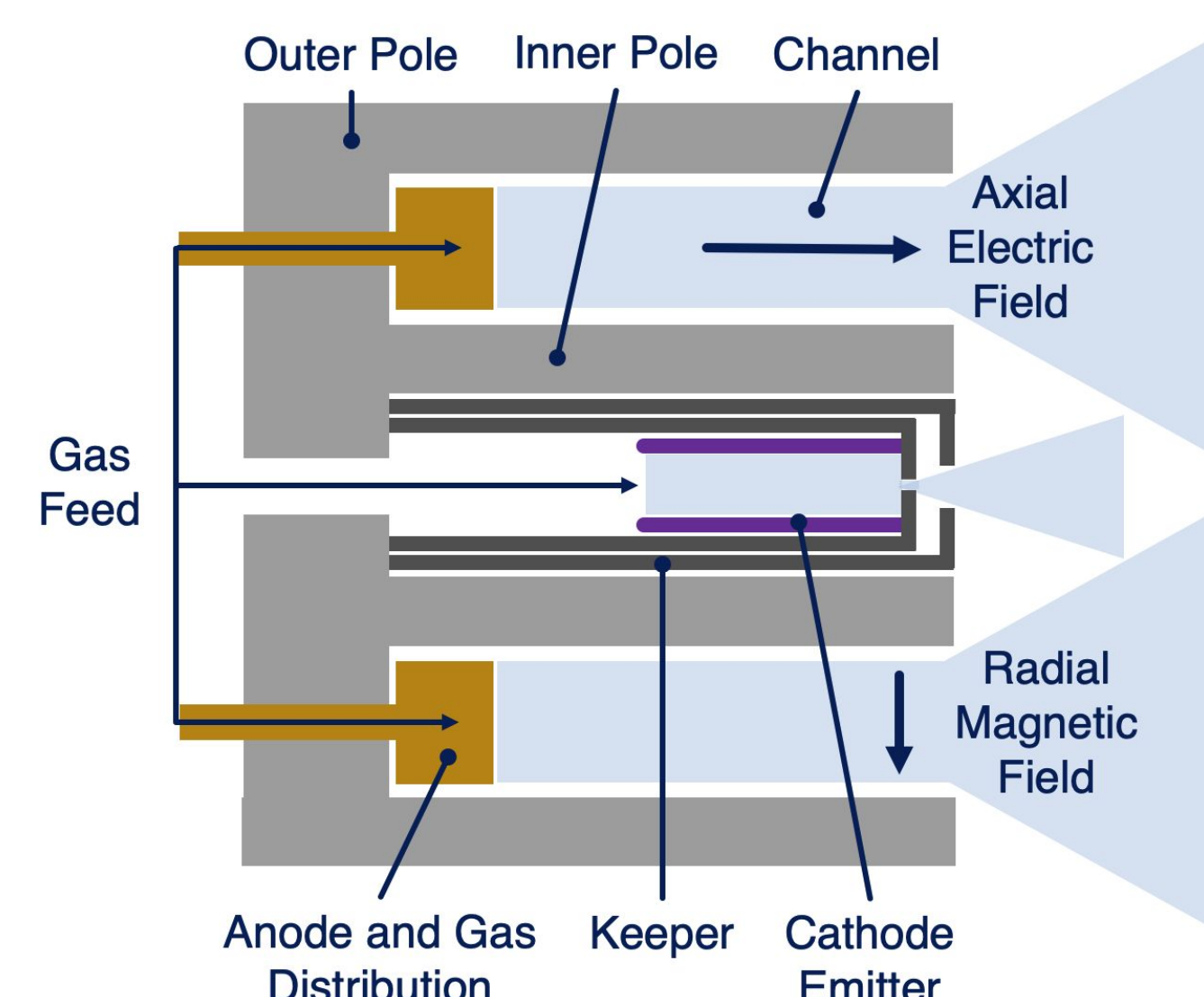
Performance of the Plume: The ACME Hall Thruster

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Plasmas and Hall Thruster Background

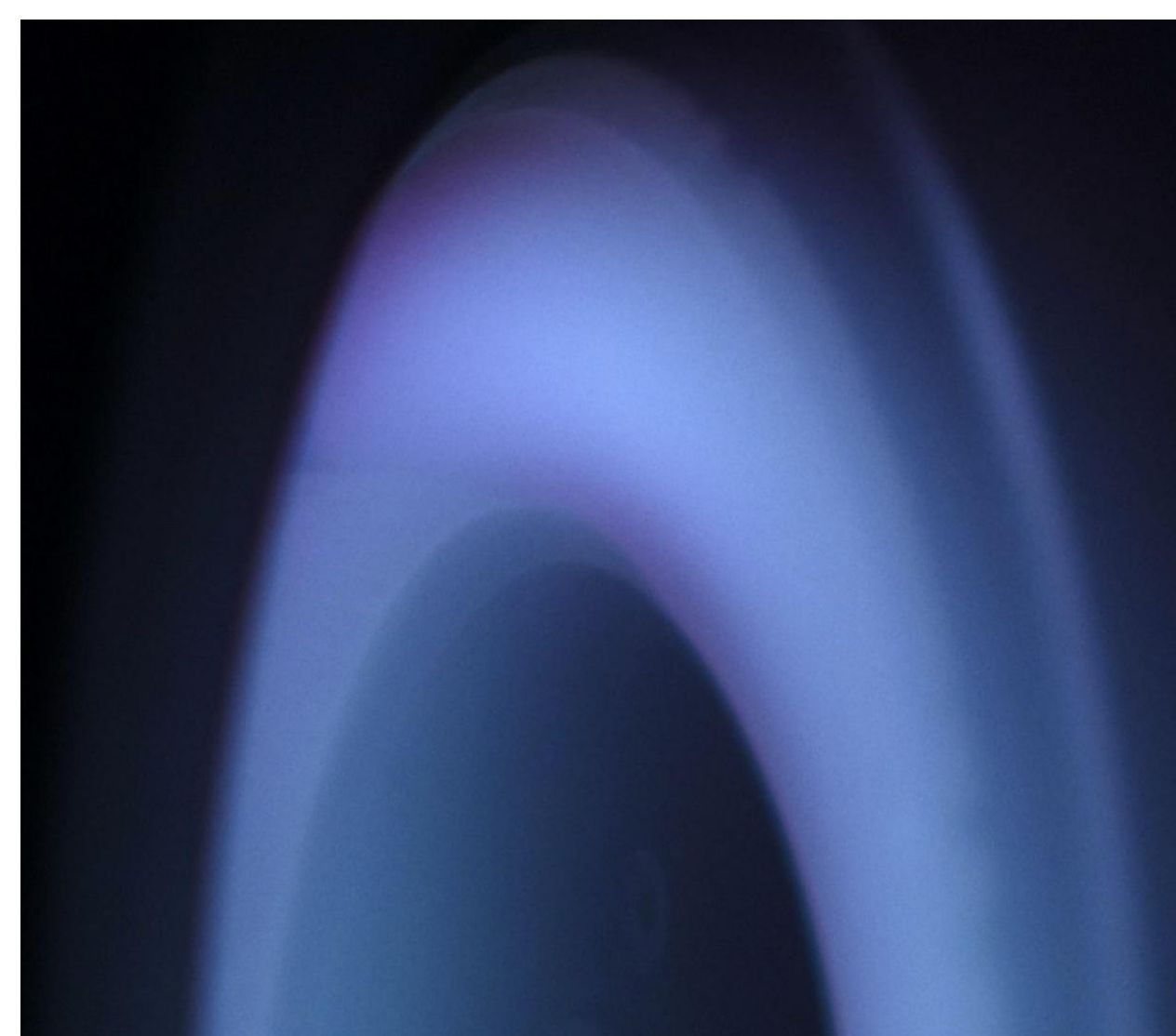
- Plasma, the 4th state of matter, consists of a quasi-neutral collection of charged particles exhibiting collective behavior
- Plasmas can be manipulated with the use of electric and magnetic fields

- Hall thrusters are a type of in-space propulsion system that utilizes plasma to generate thrust
- Ionized propellant is accelerated by an axial electric field
- The field is generated by a positively biased anode and a population of electrons trapped in the radial magnetic field near the exit plane
- These electrons drift in a circular path around the annular channel generating a Hall current



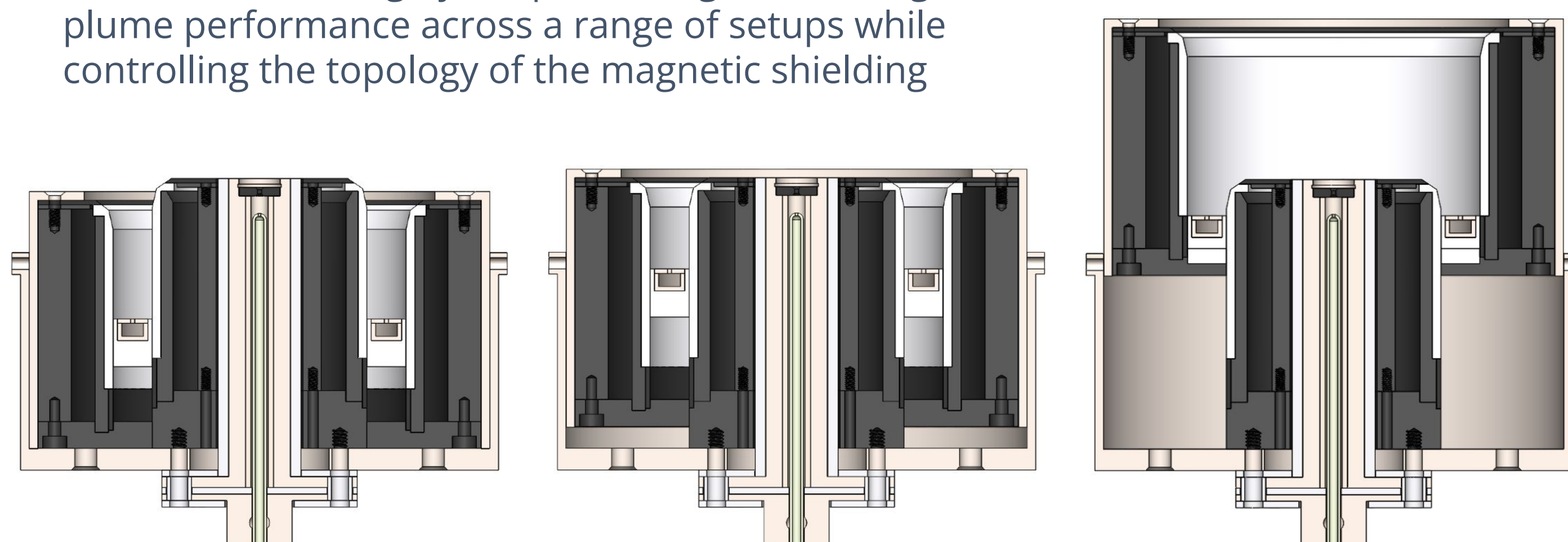
The ACME Hall Thruster

- Magnetic shielding is an evolution of Hall thruster design, enabling longer lifetimes by limiting the erosion of the walls
- The magnetic field lines of the thruster are contoured around the walls and pole caps at the exit plane
- The plasma of the Hall current, pictured right, is separated from the walls reducing both erosion and heating
- The **Adaptive-field Central-cathode Magnetically-shielded Electric thruster** (ACME) is designed to investigate the effects of this field topology on the performance of the thruster



Xenon plasma at the exit plane of ACME demonstrating the magnetic shielding

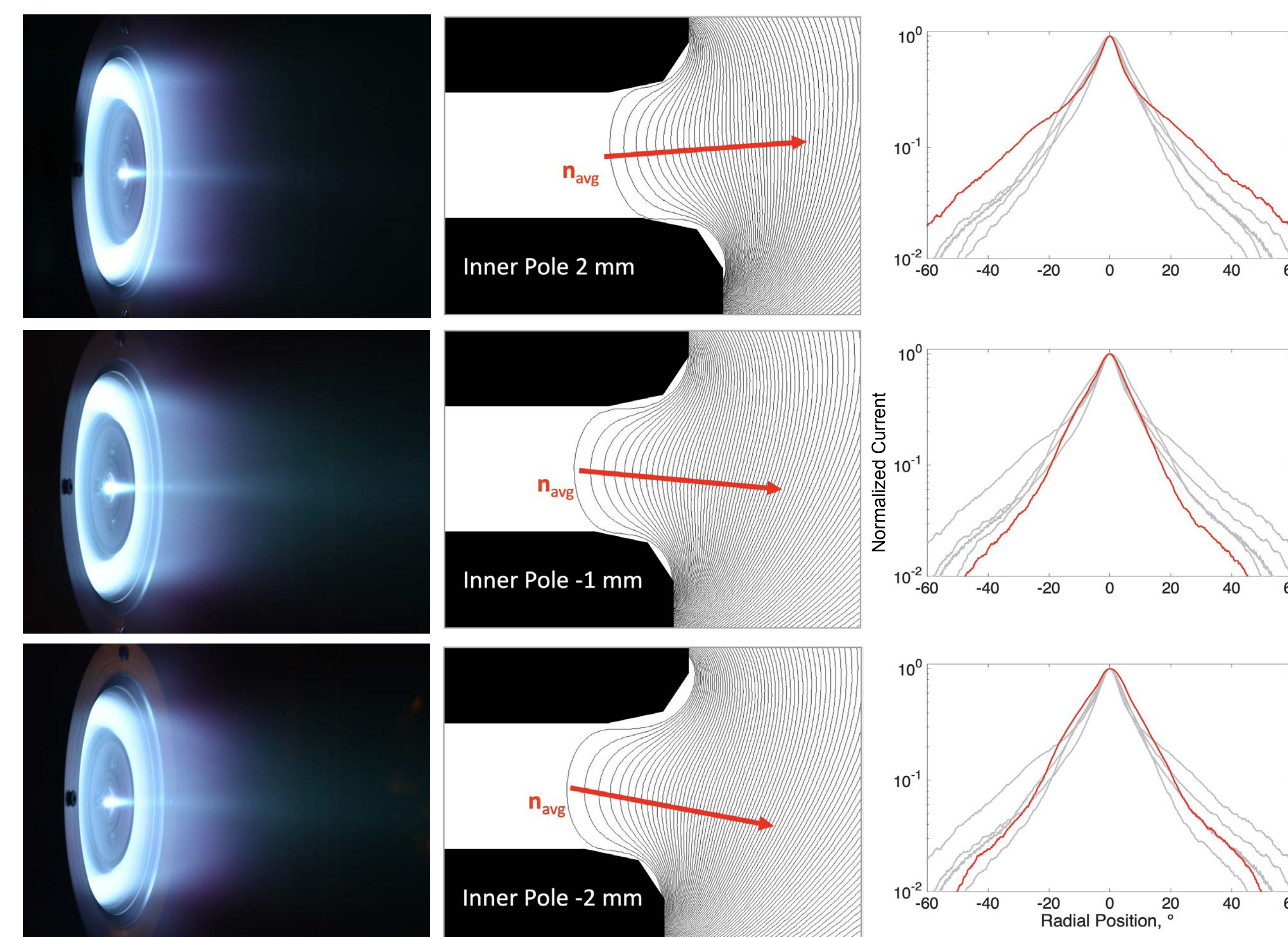
- ACME can reposition the inner and outer poles of the magnetic circuit, along with the anode, and cathode
- This allows for a highly adaptive design to investigate plume performance across a range of setups while controlling the topology of the magnetic shielding



The full range of inner pole positions ACME can operate in: Left: +5 mm, Center: 0 mm, Right: -35 mm

Focusing the Plume – Experiments on Xenon

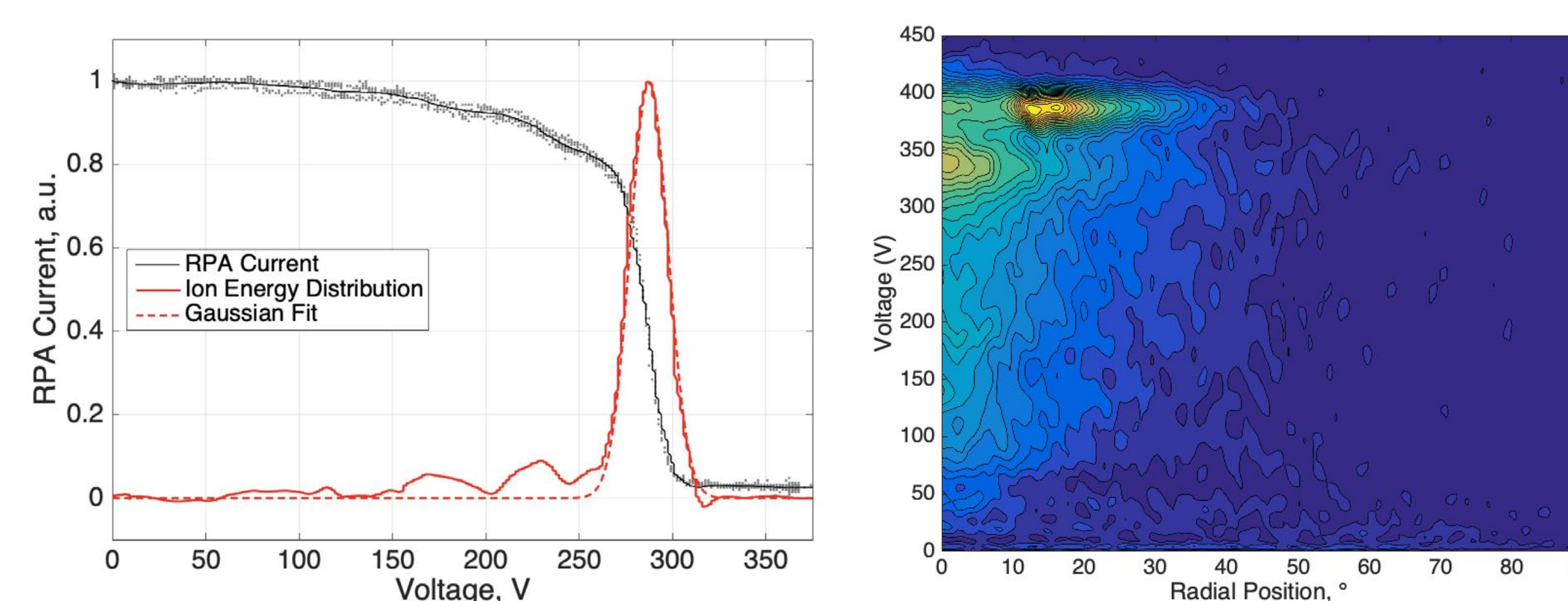
- Aim: To investigate the effects of pole position on the divergence of the plume
- Inner pole positions from +2, to -2 mm were tested at 300 V, 400 W
- The adjustable pole positions were able to change the field angle while maintaining the shielded geometry and produced a range of plume divergences from wide to over-focused.
- Swept Faraday probe measurements showed an maxima in the divergence utilization efficiency at the -1 mm pole position



The plume divergence across a subset of pole positions. (a) Photos at 105mm f/16 1/10" ISO200. (b) The simulated magnetic field with a calculated centerline acceleration vector (c) Normalized current density measurements

Plume Mapping – New Methodologies

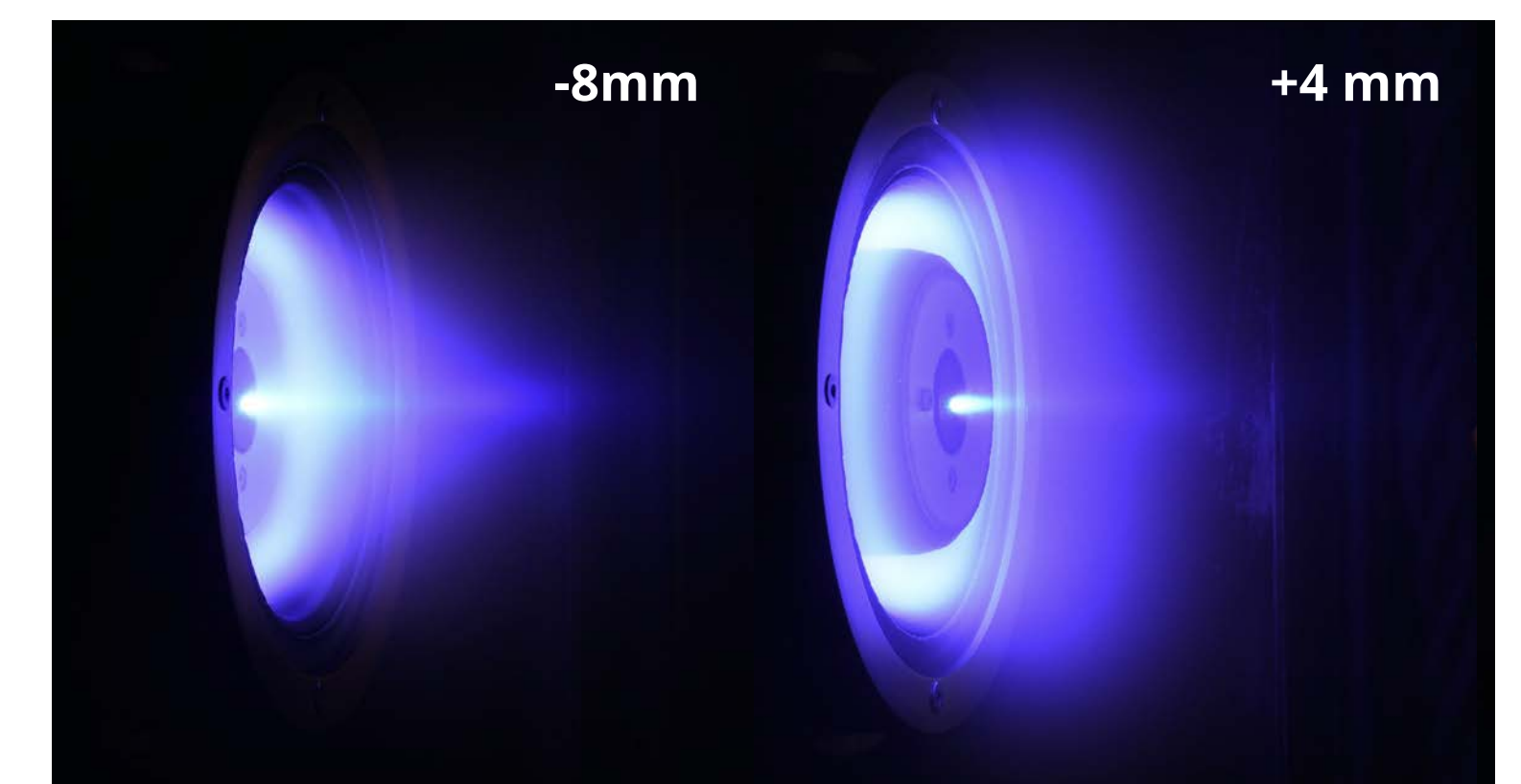
- Standard voltage utilization measurements are taken on thruster centerline using a Retarding Potential Analyzer (RPA)
- Taking a swept measurement allows the IEDF to capture the high energy ions in the plume as the beam diverges from the centerline



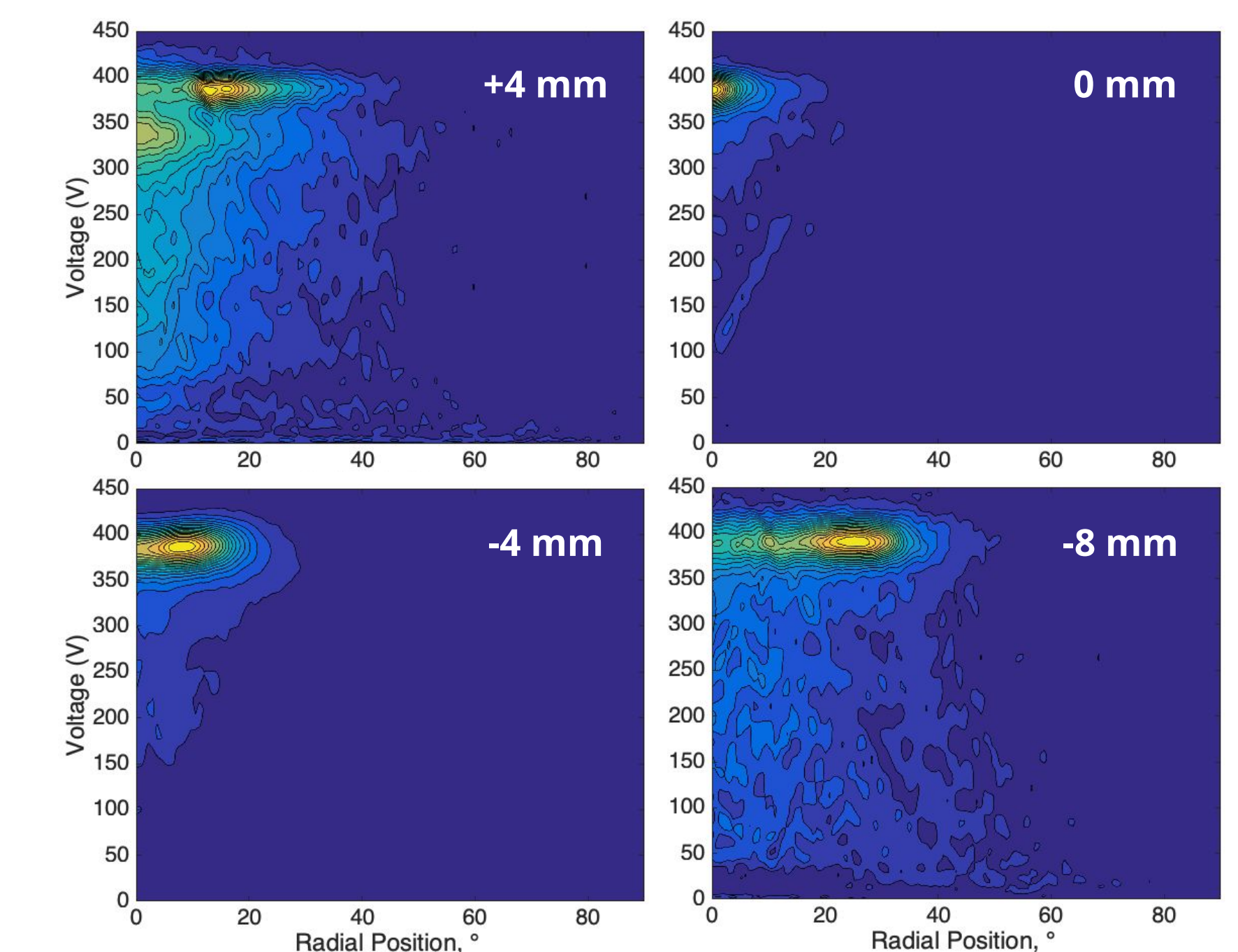
Left: A single RPA measurement taken on centerline showing the Ion Energy Distribution Function (IEDF). Right: A swept RPA showing how the IEDF varies by radial position

Mapping the Plume – Experiments on Krypton

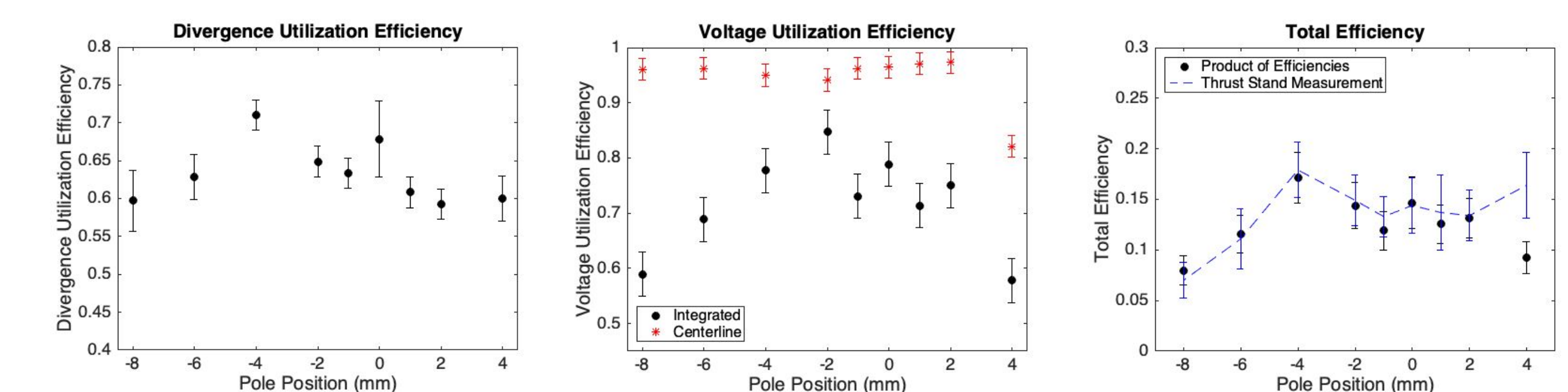
- Aims: To investigate the effects of pole position on the performance of the thruster measured with a nested inverted pendulum thrust stand at 400 V, 600 W
- To investigate each component of the efficiency from: an ExB probe, a swept Faraday probe, and a swept RPA probe
- ACME demonstrated consistent magnetic shielding across the range of pole positions tested
- The performance of the thruster shows a significant dependence on the pole positions
- IEDFs generated from the swept RPA show the improvements from the new measurement technique
- Overestimation of the voltage utilization efficiency from standard centerline measurement ranged from 9% at -2 mm, to 65 % at the -8 mm position



Plume photos at the extremes of positions tested on Kr



IEDFs of the thruster plume at +4, 0, -4, and -8 mm pole positions



- Mass and charge utilization efficiencies remained relatively consistent across the range of pole positions
- Current utilization monotonically decreased with more negative pole positions
- Both the divergence and voltage utilization efficiencies had local maxima at -4, and -2 mm respectively
- The product of the five efficiencies had good agreement with the thrust stand measurement at all but +4 mm, adding confidence to the performance analysis

Future Work

- Automated optimization of Hall thruster operating conditions using machine learning
- Updated anode design focusing on: even gas distribution, varied azimuthal injection, and water-cooling. Lead graduate student: Danny Roberts
- Lightweight and alternative propellants analysis