

## AA599: Geometric Methods for Nonlinear Control Systems

## Homework #2

Due: Tuesday April 13, 5:00pm

All problems have equal value.

1. Find the distribution generated by the vector fields in  $\mathbb{R}^3$

$$F_1 = x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x}, \quad F_2 = z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z}$$

Find a manifold in  $\mathbb{R}^3$  that includes the point  $(1, 0, 0) = (x_0, y_0, z_0)$  and has a tangent space spanned by these vector fields. (Please be careful about singular points if there are any.)

2. Find the matrix Lie algebra generated by  $A$  and  $B$

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -2 & -3 & -4 \end{bmatrix}, \quad B = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

You are free to use Mathematica or a similar program if helpful.

3. Find the reachable set from  $\dot{x}(0) = 0$ ,  $x(0) = 1$  for the control system

$$\ddot{x}(t) + (1 + u(t))x^3(t) = 0.$$

4. Do the same for the Euler rigid body equations with two applied torques

$$\dot{\omega}_1 = ((I_2 - I_3)/I_1)\omega_2\omega_3 + u_1$$

$$\dot{\omega}_2 = ((I_3 - I_1)/I_2)\omega_1\omega_3 + u_2$$

$$\dot{\omega}_3 = ((I_1 - I_2)/I_3)\omega_1\omega_2$$

5. Find the submanifold of  $\mathbb{R}^4$  that contains the point  $(w, x, y, z) = (1, 0, 0, 0)$  and has as its tangent space the distribution spanned by

$$F_1 = x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x}, \quad F_2 = z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z}, \quad F_3 = z \frac{\partial}{\partial y} - y \frac{\partial}{\partial z}$$

$$F_4 = w \frac{\partial}{\partial x} - x \frac{\partial}{\partial w}, \quad F_5 = w \frac{\partial}{\partial y} - y \frac{\partial}{\partial w}, \quad F_6 = w \frac{\partial}{\partial z} - z \frac{\partial}{\partial w}$$

6. Find the Lie algebra generated by the two vector fields

$$F_1 = x^2 \frac{\partial}{\partial z}, \quad F_2 = (z + x) \frac{\partial}{\partial x}$$