

Basics of Two-Fluid Plasma Physics—a Brief Summary

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The elementary building blocks for a multi-fluid are the canonical momentum $\mathbf{P}_a = m_a \mathbf{u}_a + q_a \mathbf{A}/c$, and the generalized vorticity $\mathbf{\Omega}_a = \nabla \times \mathbf{P}_a$ (or a-vorticity) where m_a , \mathbf{u}_a , q_a are the species mass, flow velocity and charge, and $a = i, e$ denotes the species, and \mathbf{A} is the vector potential. The quadratic invariant of a species is the self helicity, or “a-helicity,” the “density” of which is $\mathbf{P}_a \cdot \mathbf{\Omega}_a$. These are generalizations of helicities that appear in simple fluids and MHD. For zero electron mass the electron helicity reduces to the familiar magnetic helicity, an invariant in ideal MHD. The evolution of the a-helicities is governed by the helicity transport equation, derived from Maxwell’s equations and the equations of motion.

Each helicity transport equation has the form, $n_a D_a (\mathbf{P}_a \cdot \mathbf{\Omega}_a / n_a) / Dt = \nabla \cdot [(\dots) \mathbf{\Omega}_a] + \text{friction}$, where n_a is the density. The generalized vorticity appearing in the divergence term implies the existence of a “local” a-helicity associated with these lines, $K_a = (c^2/8\pi q_a^2) \dot{\mathcal{Q}} \int dt \mathbf{P}_a \cdot \mathbf{\Omega}_a$, where C is the volume occupied by a bundle of a-vortex lines. The constant factor gives K_a the convenient units of energy-length. The total derivative D_a/Dt implies that the local a-helicity convects with its own species. If an a-vortex line does not intersect the system boundary, then in the strictly ideal (frictionless) case, the associated a-helicity is constant. There is a circulation theorem, $G_a = \dot{\mathcal{Q}} \int_C \mathbf{P}_a \cdot d\mathbf{x} = \text{const}$, where C is an a-vortex line, and $d\mathbf{x}$ is a differential length vector along that line. Each species has its own set of a-vortex lines, its own local a-helicities, and its own circulation theorem.

In the realistic case with friction, visco-resistive instabilities drive reconnections that break individual a-vortex lines and destroy their identity. This is a case of non-uniform convergence because even a minute amount of friction is enough to compromise the local a-helicities. The only quantities immune to these topology altering events are the global a-helicities, $K_a = (c^2/8\pi q_a^2) \dot{\mathcal{Q}} \int dt \mathbf{P}_a \cdot \mathbf{\Omega}_a$, where V is the system volume. Even global invariants may not be *rugged* in the sense that they are *more* “invariant” than the organized energy form, *i.e.* the magnetofluid energy $W_{mf} = \dot{\mathcal{Q}} \int dt (S m_a n_a u_a^2 + B^2/8\pi)$, composed of the flow energy and the magnetic energy (the sum is over species). The ruggedness of the global a-helicities has been supported by three arguments. (1) *Selective decay*: W_{mf} decays more rapidly than K_a in thin reconnection layers. Properly applied, this argument must account for limits on viscous friction coefficients for sharp gradients. (2) *Inverse cascade*: the fluctuation spectrum of $\tilde{W}_{mf}(k)$ and $\tilde{K}_a(k)$ satisfy the necessary conditions for a cascade toward larger scale objects (k is the wave number of the disturbance). (3) *Stability to resistive modes*: K_a is less affected than W_{mf} by resistive modes. Each of these is the generalization of arguments previously applied to verify the ruggedness of the magnetic helicity in weakly-dissipative MHD.

A minimum energy state is found formally by minimizing W_{mf} subject to invariant a-helicities, and (given axisymmetric system boundary) the global angular momentum, $L_q = \dot{\mathcal{Q}} \int r S m_a n_a u_{aq}$. The variation with respect to $d\mathbf{u}_\alpha$ leads to the flow equations: $n_a (\mathbf{u}_a - \mathbf{\Omega} r \hat{\theta}) = (l_a / \ell_c^2) \mathbf{\Omega}_a$ where l_a , $\mathbf{\Omega}$ are the Lagrange multipliers associated with

invariant α -helicities and angular momentum, and $\ell_c = c/\omega_{pi} = (m_i c^2 / 4\pi e^2)^2$ is the length scale. An entropy maximization procedure subject to invariant K_a , L_q , and total energy (W_{mf} + thermal) leads to the same equation. In addition, a global Bernoulli equation links the pressure to the flow by a relation that applies throughout the system volume. Note that an important feature of a two-fluid minimum energy state is the length scale ℓ_c . A two-fluid may or may not relax to the minimum energy state depending on whether the fast mechanisms have been stabilized.

References: L.C. Steinhauer and A. Ishida, Phys. Rev. Lett. **79**, 3423 (1997); Phys. Plasmas **5**, 2609 (1998).